

Liège University finite element models for High-Temperature Superconductors

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Joint work with J. Dular and B. Vanderheyden

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Some background



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- We write quite a lot of codes, some released as open source software: https://gmsh.info, https://getdp.info, https://onelab.info



Gmsh, GetDP & ONELAB



- Gmsh (https://gmsh.info) is a 3D finite element mesh generator with a built-in CAD engine and post-processor
 - Joint work with J.-F. Remacle at UCLouvain, with important contributions from J. Lambrechts, K. Hillewaert, M. Pellikka, A. Johnen, H. Si, A. Royer, C. Marot, I. Badia, T. Toulorge, M. Reberol, ...



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- GetDP (https://getdp.info) is a general finite element solver using mixed finite elements
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- ONELAB (https://onelab.info) is an abstract interface for sharing information between codes



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- About 20,000 downloads per month (70% Windows)
- About 800 citations per year
- Gmsh has become one of the most popular open source finite element mesh generators (> 5000 citations)



Short demo

2D and 3D h- ϕ GetDP formulation for twisted HTS wires, with automatic computation of cuts using the Gmsh cohomology solver [Geuzaine, EUCAS 2015]





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To give it a try, download the ONELAB software bundle from https://onelab.info and open models/Superconductors/helix.pro







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 - Provide great flexibility in the choice of finite element formulations and associated numerical tools



• Life-HTS is about solving Maxwell's equations in the magnetodynamic (magneto-quasistatic) approximation

$$\operatorname{curl} \boldsymbol{h} = \boldsymbol{j}, \quad \operatorname{curl} \boldsymbol{e} = -\partial_t \boldsymbol{b}, \quad \operatorname{div} \boldsymbol{b} = 0,$$

with

- h the magnetic field (A/m),
- j the current density (A/m²),
- e the electric field (V/m), and
- **b** the magnetic flux density (T),

while the displacement current $\partial_t d$ is neglected



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- Boundary conditions and constitutive laws relating b to h and e to j are needed to obtain a well-posed problem



• In ferromagnetic materials: classical anhysteretic saturation law, or energy-based hysteresis model [Jacques et al., AIP Advances 2018]



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- In high-temperature superconductors: $oldsymbol{e}=
 ho(oldsymbol{j})oldsymbol{j}$ with power law



$$ho(\boldsymbol{j}) = rac{e_c}{j_c} \left(rac{||\boldsymbol{j}||}{j_c}
ight)^{n-1}$$

with

•
$$e_c = 10^{-4} \text{ V/m}$$

- j_c the critical current density
- n the flux creep exponent $(n \in [10, 1000])$

[Plummer & Evetts, IEEE TAS 1987; Zeldov et al., Appl. Phys. Lett. 1990]



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$$\begin{array}{c} (\phi, \omega) \xrightarrow{\operatorname{grad}_{h}} \boldsymbol{h} (\boldsymbol{t}) \xrightarrow{\operatorname{curl}_{h}} \boldsymbol{j} \xrightarrow{\operatorname{div}_{h}} \boldsymbol{0} \\ & & & & \\ & & & \\ & & & \\ & & & \\ 0 \xleftarrow{\operatorname{div}_{e}} \boldsymbol{b} \xleftarrow{\operatorname{curl}_{e}} \boldsymbol{e} (\boldsymbol{a}, \boldsymbol{a}^{*}) \xleftarrow{\operatorname{grad}_{e}} (\boldsymbol{v}) \end{array}$$

- *h*-conform formulations (*h*, *h*- ϕ , *t*- ω , ...) satisfy the top exactly
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- *h*-conform formulations (*h*, *h*- ϕ , *t*- ω , ...) satisfy the top exactly
- b-conform formulations (a, a-v, a*, ...) satisfy the bottom exactly
- The choice of the formulation has a significant effect on the numerical performance of the finite element solver



<i>h</i> -conform	HTS	Ferromagnetic material	
Constitutive law			
Linearization	Newton-Raphson	Picard	

b -conform	HTS	Ferromagnetic material	
Constitutive law	j e	h b	
Linearization	Picard	Newton-Raphson	

[Dular, Geuzaine & Vanderheyden, IEEE TAS 2019]



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 - The number of degrees of freedom (depending on the polynomial approximation order) and the structure of the resulting matrices



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- For problems with both HTS and ferromagnetic parts, coupling h- and b-conform formulation leads to the best results
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- Additional flexibility is required for handling HTS tapes: thin shell approximation (or not), homogenization of multiple tapes (or not), ...



- h- and b-conform formulations, uncoupled or coupled (h, h- ϕ , t- ω , a, a-v, a^* , h-(ϕ -)a, t-a, ...):
 - to provide optimal numerical efficiency depending on the situation at hand
 - suitable for HTS bulks and tapes, possibly combined with ferromagnetic materials



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- First and second order finite elements bases for H^1 , $H({\rm curl})$, $H({\rm div})$ and L^2



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- Stable linearization schemes for dealing with non-linear constitutive laws: Newton-Raphson and Picard schemes, with adaptive relaxation
- Easy coupling of fields and formulations, staggered or monolithic, for multi-physics coupling (mechanical, thermal)
 - E.g. explicit Jacobian for strongly coupled magneto-thermal problem



- Transient analysis with adaptive time stepping (Euler, Crank-Nicholson and BDF schemes) for calculating
 - field maps
 - magnetization
 - eddy currents
 - losses
 - ...



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- Parameterizable graphical user interface through ONELAB
 - control any simulation parameter
 - construct application-specific tools for both education and industry



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 - the input data defining discrete problems (written in plain text .pro files), and
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- At the core of template .pro files, weak formulations are written symbolically



For example, in a .pro file, the weak formulation: Find $u(x) \in H^1_0(\Omega)$ such that

$$-\int_{\Omega} a(x)\nabla u \cdot \nabla u' \, d\Omega = \int_{\Omega} f(x) \, u' \, d\Omega, \quad \forall u' \in H^1_0(\Omega)$$

is transcribed as

```
Formulation{
    { Name MyFirstFormulation; Type FemEquation;
    Quantity {
        { Name u; Type Local; NameOfSpace H1_0; }
    }
    Equation {
        Integral { [ -a[] * Dof{d u}, {d u} ];
        In Omega; Integration I; Jacobian J; }
        Integral { [ -f[], {u} ];
        In Omega; Integration I; Jacobian J; }
    }
}
```



Similarly, here is a bare-bones h or $h-\phi$ formulations (they are the same—only the function space HSpace changes!)

```
Formulation {
  { Name MagDynH; Type FemEquation;
    Quantity {
     { Name h; Type Local; NameOfSpace HSpace; }
    }
    Equation {
      Integral { DtDof [ mu[] * Dof{h} , {h} ];
        In Omega; Integration Int; Jacobian Vol; }
      Integral { [ rho[{d h}] * {d h} , {d h} ];
        In OmegaC; Integration Int; Jacobian Vol; }
      Integral { [ dEdJ[{d h}] * Dof{d h} , {d h} ];
        In OmegaC; Integration Int; Jacobian Vol; }
      Integral { [ - dEdJ[{d h}] * {d h} , {d h} ];
        In OmegaC ; Integration Int; Jacobian Vol; }
   }
 }
}
```



Examples



3D HTS Magnet Motor Pole Modelling



One eight of the geometry (air domain not shown)

.

Formulation	Function space	Support of DOFs	$\sigma \neq 0$ in $\Omega_{\rm c}^{\rm C}$?
<i>h</i> -formulation	$\mathcal{H}(\Omega) = \{ \boldsymbol{h} \in H(\mathbf{curl}; \Omega) \}$	Edges in Ω	Yes
h - ϕ -formulation	$\mathcal{H}_{\phi}(\Omega) = \{ \boldsymbol{h} \in H(\operatorname{curl}; \Omega) \mid \operatorname{curl} \boldsymbol{h} = \boldsymbol{0} \text{ in } \Omega_{c}^{C} \}$	Edges in Ω_c , nodes in Ω_c^C	No
\bar{a} -formulation	$\bar{\mathcal{A}}(\Omega) = \{ \boldsymbol{a} \in H(\mathbf{curl}; \Omega) \}$	Edges in Ω	(Yes)
a-formulation	$\mathcal{A}(\Omega) = \{ \boldsymbol{a} \in H(\mathbf{curl}; \Omega) \mid \text{co-tree gauge in } \Omega_{c}^{C} \}$	Edges in Ω_c , facets in Ω_c^C	No
<i>h-a-</i> formulation	$h \in \mathcal{H}(\Omega_{c}), a \in \mathcal{A}(\Omega_{c}^{C})$	Edges in Ω_c , facets in Ω_c^C	No
h - ϕ - a -formulation	$oldsymbol{h}\in\mathcal{H}_{\phi}(\Omega_{a}),oldsymbol{a}\in\mathcal{A}(\Omega_{a})$	Edges in $\Omega_{h,c}$, nodes in $\Omega_{h,c}^{C}$, facets in Ω_{a}	No



3D HTS Magnet Motor Pole Modelling



Current density in the bulk during magnetizing pulse and relaxation

[Dular et al., 2021]

Formulation	# DOFs	# iterations	CPU time
<i>h</i> -formulation	35,532	4,057	5h58
$oldsymbol{h}$ - ϕ -formulation	12,172	3,937	3h38
$ar{a}$ -formulation	29,010	2,955	4h45
\boldsymbol{a} -formulation	26,964	3,147	3h07
h- a -formulation	32,045	1,124	1h25
$m{h}$ - ϕ - $m{a}$ -formulation	16,070	1,108	1h16



Improving HTS magnetic shields with a soft ferromagnetic material

Shielding an axial field with a HTS tube



Shielding with an additional ferromagnetic tube



[Lousberg et al., TAS 2010]



Protecting a bulk HTS against crossedfield demagnetisation with a ferromagnetic layer

Sequence of applied fields



Current distribution in the bulk with a ferromagnetic top layer ($\mu_r = 10, 100$)



[Fagnard et al., SUST 2016]



Magnetic shielding in inhomogeneous fields





[Hogan et al., SUST 2018]



Magnetic shielding, bulk superconducting cylinders and caps

Tracking stray fields in composite shields



Induced currents vs. geometries



[Fagnard et al., SUST 2019]



Critical states in stacked Niobium films

Peculiar patterns of discontinuity lines in stacks of Nb films



 $L=200~\mu{\rm m},~d=t=300~{\rm nm}$

Needs to include a genuine $J_c(B)$ -dependence!

Raising field stage







[Burger et al., SUST 2019]



Critical states in the presence of a ratchet pinning potential

Experiment: rotation of the central discontinuity line in the decreasing field stage, after magnetization



Model: an anisotropic pinning force reproduces the result



[Motta et al., Phys. Rev. B, in press.]



Rotating HTS motor





B [mT]

d [mm]

2D axisymmetric model of moving bulk superconductors



[Houbart & Vanderbemden, 2021]



Coil of HTS Tapes

 $h\text{-}a^*$ formulation with thermal coupling; tapes in parallel, series or end-coupled



Good agreement with reference results from COMSOL

[Schnaubelt, Bortot & Schöps, 2021]





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 - Improved solvers for large scale problems



Thanks for your attention

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